

# Social Robots and Applications in Special Education



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# 1. Special Education

Special Education concerns at least 10% of the world's children; i.e., children with autism, dyslexia, dyscalculia etc.

Typically, in Special Education (human) teachers are employed for personal treatment.

Lately, Social Robots (including NAO by Aldebaran) are employed effectively in Special Education.



## 2. Social Robots Examples

- Jibo: video "Jibo.mp4"
- Pepper: video "Pepper.mp4"
- NAO: video "NAO.mp4"

## 3. Economic Perspectives

The development of social robot and supportive technologies applications in Special Education is a production with the following features:

- High added value.
- Multidisciplinary.
- The end-product concerns a substantial percentage (>10%) of the human population, worldwide.

## 4. Our Software

We pursue a multi-disciplinary collaboration of Special Education teachers, psychologists and other specialties with engineers to develop innovative applications.

We use Social Robots as tools/assistants to human teachers.



## 5. Our Application

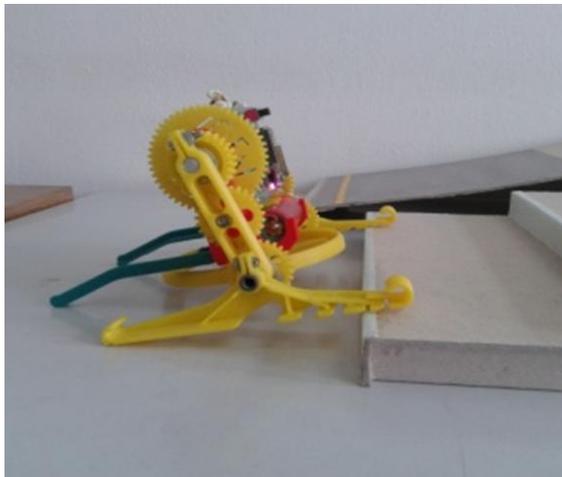
NAO in autism: video "naoforchina3.mp4"

The NAO is **autonomous** rather than tele-operated.



## 6. "Our" Hardware

Collaborating with colleagues from the Institute of Robotics, Bulgarian Academy of Sciences in Sofia, Bulgaria we develop simple Social Robots in a social context.





## 8. Supportive Technologies

- Novel, supportive technologies in Special Education:

A number of useful (diagnostic and educational) practices in “paper and pencil” can be implemented using a combination of computing devices (e.g., Tablets) and advanced sensors (e.g., Kinect).

# 9. Social Robots in Europe

European Union



Paolo Dario

Robot Companions for Citizens ++

The interest focuses on the elderly.

We want to focus on Special Education.

# 10. Future Direction

It appears that the **critical obstacle** to the proliferation of social robots and supportive technologies in Special Education is their **intelligence**.



# 11. Future Direction

Perhaps, a new paradigm for modeling human intelligence is necessary.

<https://repository.kallipos.gr/handle/11419/3443>



# 12. Our Instrument

- We have introduced the “Lattice Computing (LC)” paradigm for rigorous modeling based on disparate types of data including numerical and/or non-numerical data.

See also in:

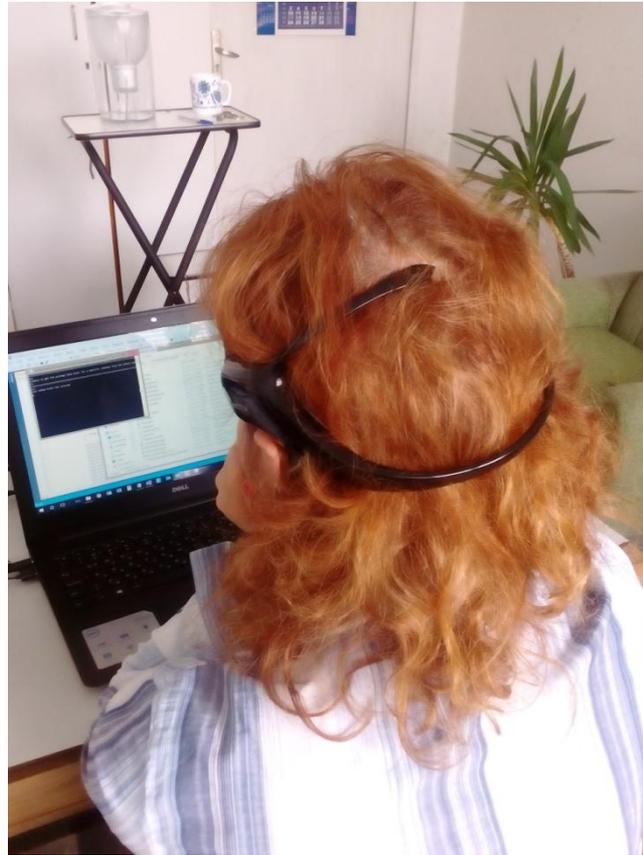
V.G. Kaburlasos, G.A. Papakostas, “Learning distributions of image features by interactive fuzzy lattice reasoning (FLR) in pattern recognition applications”, *IEEE Computational Intelligence Magazine*, vol. 10, no. 3, pp. 42-51, 2015.

# 13. Our Proposal

- Our interest is in supporting an industrial production of innovative Social Robot platforms (build in China) driven by innovative human-machine interaction models in Special Education applications.

# 14. Brain-Robot Interfaces

Novel interfaces  
in brain-robot  
interaction –  
Emotiv.



Objective:  
Issue commands  
to a robot from  
the brain

**Thank you**

